EE364M EXERCISE SET 7

Due date: February 28, 11:59pm

Question 7.1 (An efficient representation of robustness): In robust optimization problems, one has uncertain problem data: abstractly, there is an uncertainty set \mathcal{U} capturing potential noise, and we wish to guarantee that problem constraints are satisfied for all potential values $u \in \mathcal{U}$. This (abstractly) gives rise to convex optimization problems of the form

minimize
$$f(x)$$

subject to $g_i(x, u) \le 0$ for all $u \in \mathcal{U}, \quad i = 1, \dots, m,$ (7.1)

where for each $u \in \mathcal{U}$, $g_i(\cdot, u)$ is convex. See, for example, the book [1] for much much more on such problems. The challenge is that, while the problem (7.1) is convex whenever f is, the constraints in problem (7.1) are typically infinite, making efficient computation challenging; a common approach is to use duality to obtain an alternative representation of the constraint $g_i(x, u) \leq 0$ for all $u \in \mathcal{U}$ that is efficiently representable. Typical choices for \mathcal{U} include sets defined by probability distributions, so that \mathcal{U} covers (say) a $1 - \alpha$ fraction of possible realizations of noise u in a system.

Recall the ℓ_2 -operator norm $|||A|||_{op} = \sup\{u^T Av \mid ||u||_2 = ||v||_2 = 1\}$. Fix (nominal) problem data A_0, b , let $\gamma \ge 0$, and consider the constraint that $(x, t) \in \mathbb{R}^n \times \mathbb{R}_+$ satisfy

$$\|(A_0 + \Delta)x + b\|_2 \le t \quad \text{for all} \quad \|\Delta\|_{\text{op}} \le \gamma.$$

$$(7.2)$$

Show that (x, t) satisfy the constraint (7.2) if and only if there exists $\lambda \ge 0$ such that

$$\begin{bmatrix} tI_n - \lambda I_n & 0 & (A_0x+b) \\ 0 & \lambda I_n & \gamma x \\ (A_0x+b)^T & \gamma x^T & t \end{bmatrix} \succeq 0.$$

Hints. In my solution, I used the following results. If you use Lemma 7.1.1, you should prove it. You may assume Lemmas 7.1.2 and 7.1.3.

Lemma 7.1.1. Let $K = \{(x,t) \mid ||x||_2 \leq t\}$ be the Lorentz cone. Then $(x,t) \in K$ if and only if

$$\begin{bmatrix} tI & x \\ x^T & t \end{bmatrix} \succeq 0.$$

Lemma 7.1.2 (Schur complements). Let A, B, C be matrices of appropriate size. Then

$$M = \begin{bmatrix} A & B \\ B^T & C \end{bmatrix} \succeq 0$$

if and only if $A \succeq 0$, $C - B^T A^{\dagger} B \succeq 0$, and span(A) contains the columns of B.

Using these, I showed that the constraint (7.2) was equivalent to

$$t \|v\|_{2}^{2} + ts^{2} + 2sv^{T}(A_{0}x + b) - 2\gamma su^{T}x \ge 0 \text{ whenever } \|v\|_{2}^{2} \ge \|u\|_{2}^{2}, \ s \in \mathbb{R}.$$
 (7.3)

Now apply

Lemma 7.1.3 (Inhomogeneous S-Lemma). Assume the constraint qualification that there exists \overline{x} such that $\overline{x}^T A_0 \overline{x} + 2b_0^T \overline{x} + c_0 > 0$. Then the following two statements are equivalent:

$$x^{T}A_{0}x + 2b_{0}^{T}x + c_{0} \ge 0$$
 implies $x^{T}A_{1}x + 2b_{1}^{T}x + c_{1} \ge 0$

and

$$\begin{bmatrix} A_1 - \lambda A_0 & b_1 - \lambda b_0 \\ (b_1 - \lambda b_0)^T & c_1 - \lambda c_0 \end{bmatrix} \succeq 0 \text{ for some } \lambda \ge 0.$$

References

 A. Ben-Tal, L. E. Ghaoui, and A. Nemirovski. *Robust Optimization*. Princeton University Press, 2009.